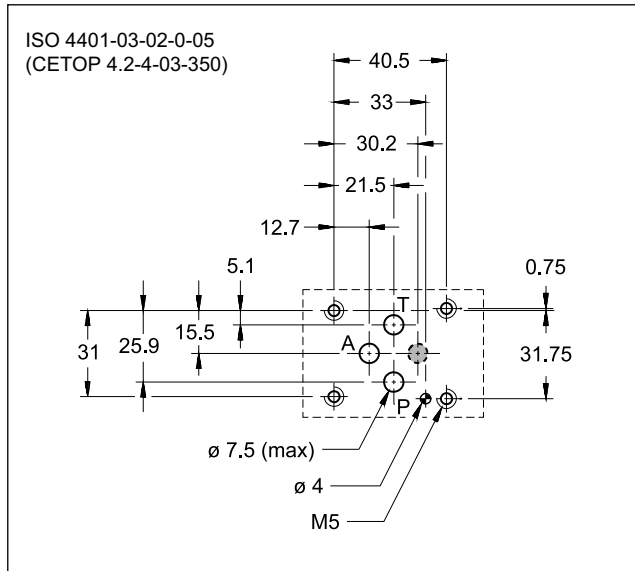![Duplomatic Motion Solutions logo]

PZE3G*

PROPORTIONAL THREE-PORT PRESSURE REDUCING VALVE, PILOT OPERATED, WITH INTEGRATED ELECTRONICS
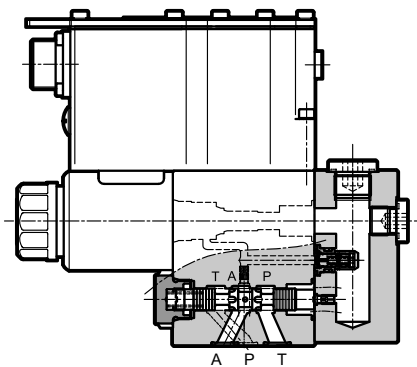
SUBPLATE MOUNTING
ISO 4401-03

p max **350** bar
Q max **40** l/min

MOUNTING SURFACE

ISO 4401-03-02-0-05
(CETOP 4.2-4-03-350)

OPERATING PRINCIPLE

— PZE3G* valve is a proportional three-port pressure reducing valve, pilot operated, with on-board electronics with mounting surface according to ISO 4401-03 standards.

— This valve controls the outlet pressure on port A, reducing the inlet pressure from line P or relieving the overpressure from line A into T keeping it at the set value. (typically: hydraulic counter-weight or load balancing)
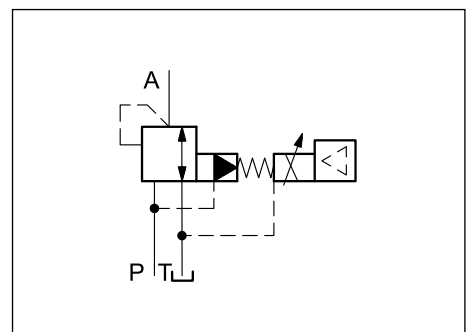
— It is suitable to modulate the pressure in hydraulic circuits.

— It is available with different types of electronics, with analogue or fieldbus interfaces.

— Valves are easy to install. The driver directly manages digital settings.

PERFORMANCES
(obtained with mineral oil with viscosity of 36 cSt at 50°C and p = 140 bar)

Maximum operating pressure: - P port - T port	bar	350 2
Maximum flow (see p max = f(Q) diagram)	l/min	40
Step response	see point 7	
Hysteresis	% of p nom	< 3%
Repeatability	% of p nom	< ±1%
Electrical characteristic	see point 2	
Ambient temperature range	°C	-20 / +60
Fluid temperature range	°C	-20 / +80
Fluid viscosity range	cSt	10 ÷ 400
Fluid contamination degree	According to ISO 4406:1999 class 18/16/13	
Recommended viscosity	cSt	25
Mass	kg	2.7

HYDRAULIC SYMBOL

1 - IDENTIFICATION CODE

1.1 - Standard electronics

| P | Z | E | 3 | G | - | | / | 31 | | - | | K11 | | |

Three-port pressure reducing valve, pilot operated

Electrical proportional control

Size ISO 4401-03

Standard electronics for open loop

Pressure control range:
025 = 0 ÷ 25 bar
070 = 0 ÷ 70 bar
140 = 0 ÷ 140 bar
210 = 0 ÷ 210 bar
310 = 0 ÷ 310 bar

Series No.
(the overall and mounting dimensions remain unchanged from 30 to 39)

Seals:
N = NBR seals for mineral oil (**standard**)
V = FPM seals for special fluids

Reference signal:
E0 = voltage 0 ÷ 10 V
E1 = current 4 ÷ 20 mA

Connection 6 pin + PE

Pin C function:
A = external enable
B = internal enable
C = 0V monitor

Option:
/ W7 = zinc-nickel surface treatment (see p. 1.2)
Omit if not required.
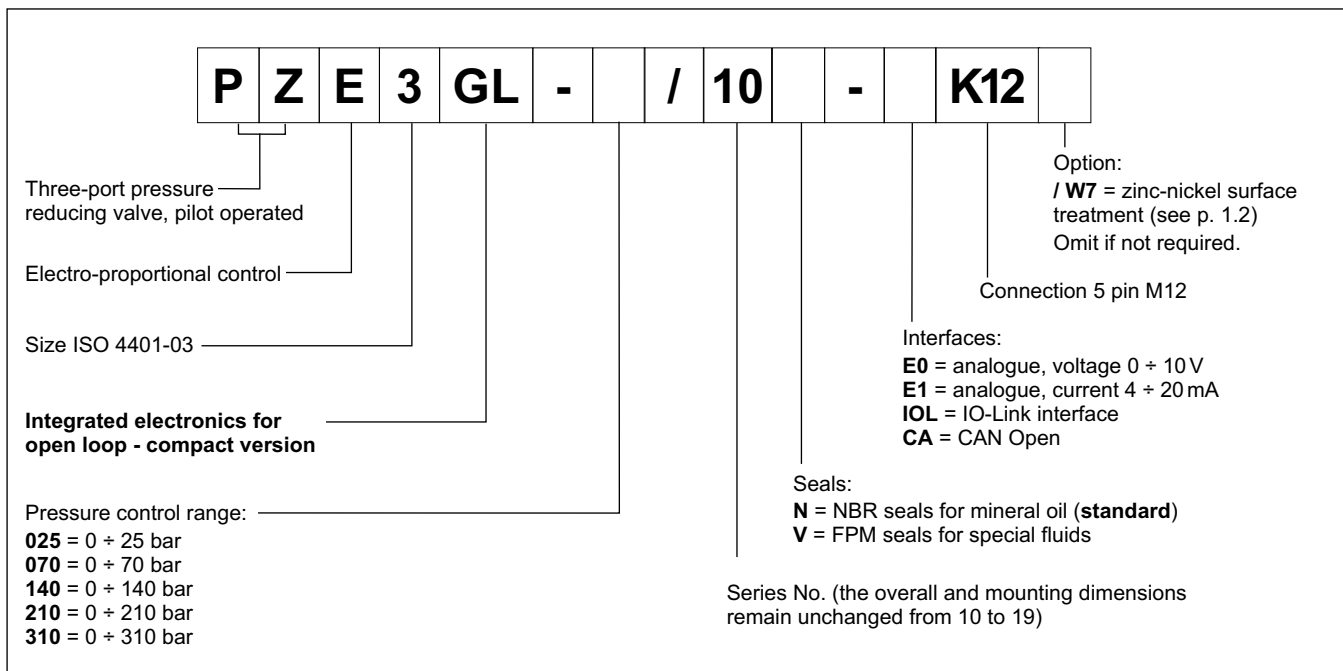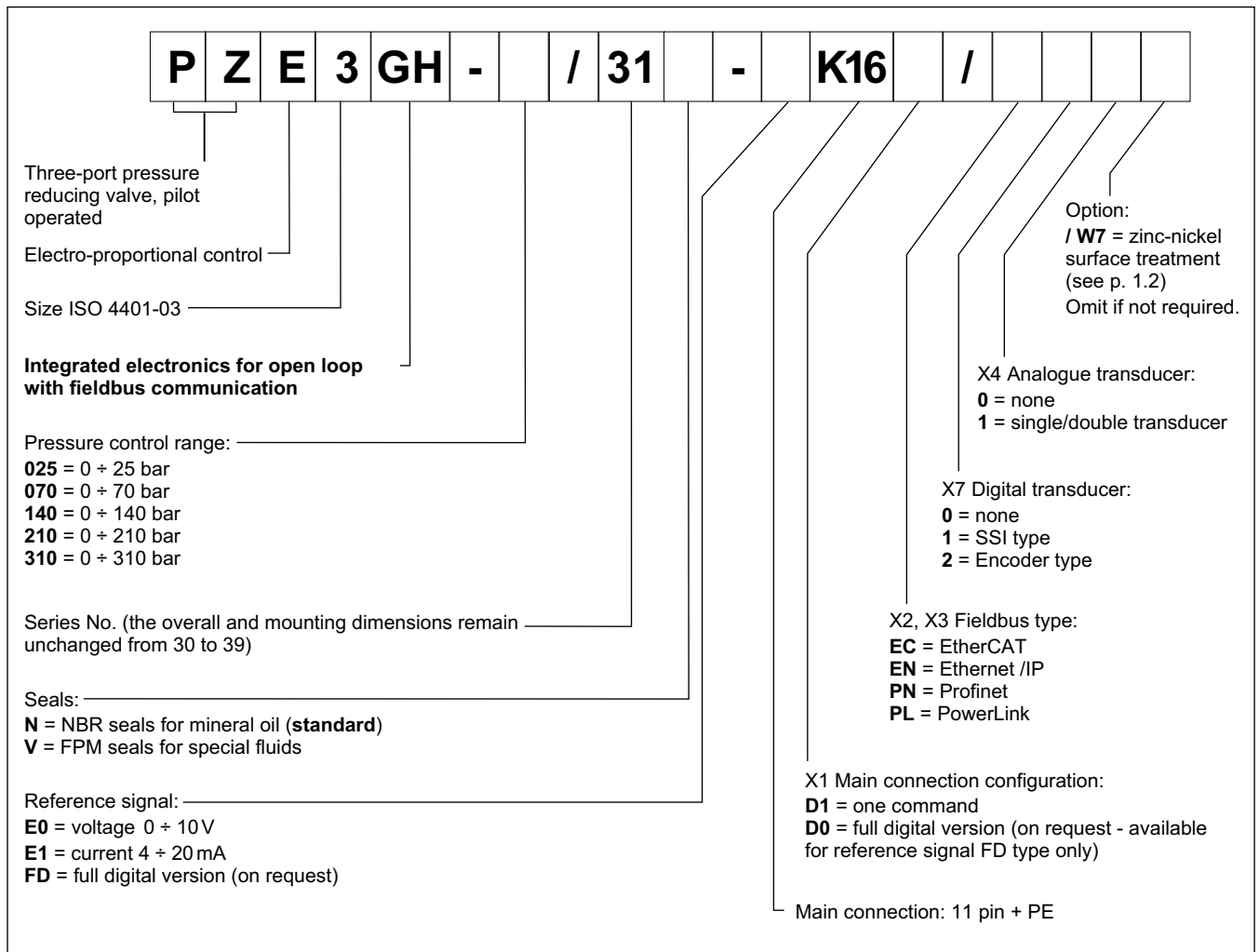
1.2 - Surface treatments

The standard valve is supplied with surface treatment of phosphating black. The zinc-nickel finishing on the valve body makes the valve suitable to ensure a salt spray resistance up to 240 hours. (test operated according to UNI EN ISO 9227 standards and test evaluation operated according to UNI EN ISO 10289 standards).

1.3 - Compact electronics

| P | Z | E | 3 | GL | - | | / | 10 | | - | | K12 | | |

Three-port pressure reducing valve, pilot operated

Electro-proportional control

Size ISO 4401-03

Integrated electronics for open loop - compact version

Pressure control range:
025 = 0 ÷ 25 bar
070 = 0 ÷ 70 bar
140 = 0 ÷ 140 bar
210 = 0 ÷ 210 bar
310 = 0 ÷ 310 bar

Series No. (the overall and mounting dimensions remain unchanged from 10 to 19)

Seals:
N = NBR seals for mineral oil (**standard**)
V = FPM seals for special fluids

Interfaces:
E0 = analogue, voltage 0 ÷ 10 V
E1 = analogue, current 4 ÷ 20 mA
IOL = IO-Link interface
CA = CAN Open

Connection 5 pin M12

Option:
/ W7 = zinc-nickel surface treatment (see p. 1.2)
Omit if not required.

PZE3G*

1.4 - Electronics with fieldbus communication

| P | Z | E | 3 | GH | - | | /31 | - | K16 | / | | | | |

Three-port pressure reducing valve, pilot operated

Electro-proportional control

Size ISO 4401-03

Integrated electronics for open loop with fieldbus communication

Pressure control range:
025 = 0 ÷ 25 bar
070 = 0 ÷ 70 bar
140 = 0 ÷ 140 bar
210 = 0 ÷ 210 bar
310 = 0 ÷ 310 bar

Series No. (the overall and mounting dimensions remain unchanged from 30 to 39)

Seals:
N = NBR seals for mineral oil (**standard**)
V = FPM seals for special fluids

Reference signal:
E0 = voltage 0 ÷ 10 V
E1 = current 4 ÷ 20 mA
FD = full digital version (on request)

Option:
/ W7 = zinc-nickel surface treatment (see p. 1.2)
Omit if not required.

X4 Analogue transducer:
0 = none
1 = single/double transducer

X7 Digital transducer:
0 = none
1 = SSI type
2 = Encoder type

X2, X3 Fieldbus type:
EC = EtherCAT
EN = Ethernet /IP
PN = Profinet
PL = PowerLink

X1 Main connection configuration:
D1 = one command
D0 = full digital version (on request - available for reference signal FD type only)

Main connection: 11 pin + PE

2 - ELECTRONICS COMMON DATA

Duty cycle		100% (continuous operation)
Protection class according to EN 60529		IP65 / IP67 (**NOTE**)
Supply voltage	V DC	24 (from 19 to 30 VDC), ripple max 3 Vpp
Power consumption	VA	25
Maximum solenoid current	A	1.88
Fuse protection, external	A	2A time lag
Managed breakdowns		Overload and electronics overheating, cable breakdown, supply voltage failures
Electromagnetic compatibility (EMC) emissions EN 61000-6-4, immunity EN 61000-6-2		According to 2014/30/EU standards

NOTE: The IP degree is guaranteed only with mating connector of equivalent IP degree, installed and tightened correctly. Moreover, on the GH versions it is necessary to protect with caps any unused connections.

3 - PZE3G - STANDARD ELECTRONICS

3.1 - Electrical characteristics

Command signal: voltage (E0) current (E1)	V DC mA	0 ÷ 10 (Impedance Ri = 11 kOhm) 4 ÷ 20 (Impedance Ri = 58 Ohm)
Monitor signal (current to solenoid): voltage (E0) current (E1)	V DC mA	0 ÷ 10 (Impedance Ro > 1 kOhm) 4 ÷ 20 (Impedance Ro = 500 Ohm)
Communication for diagnostic		LIN-bus Interface (by means of the optional kit)
Connection		6 pin + PE (MIL-C-5015-G - DIN EN 175201-804)

3.2 - On-board electronics diagrams

VERSION A - External Enable
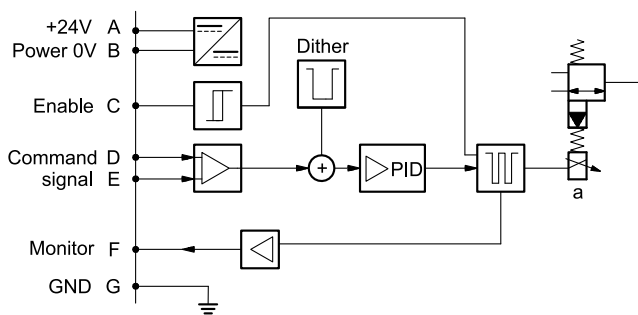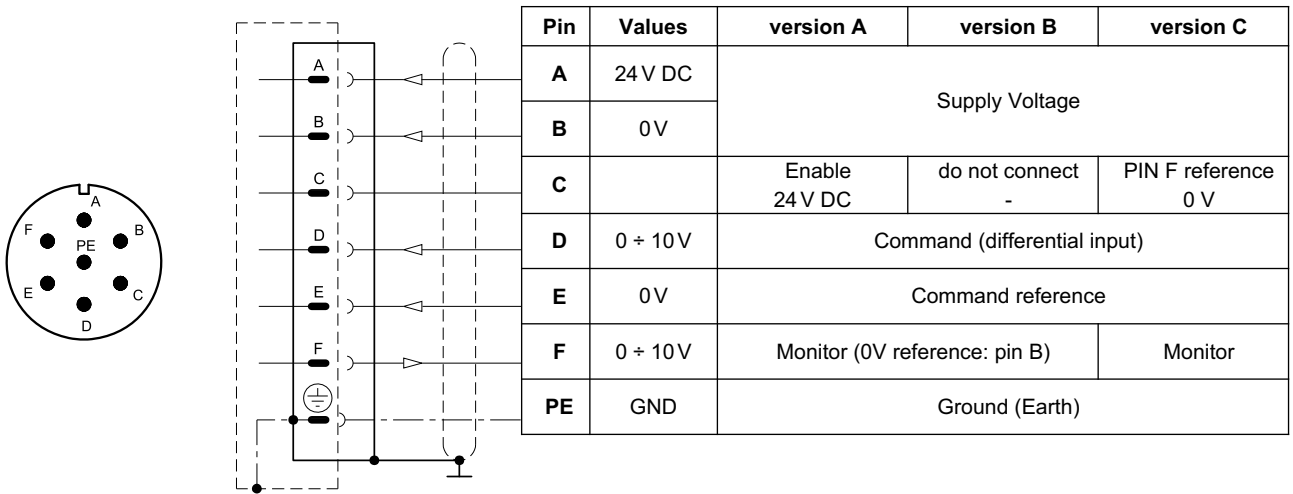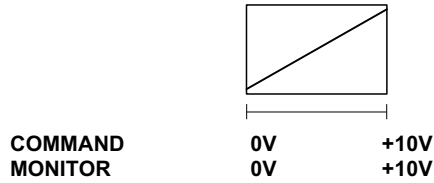

VERSION B - Internal Enable
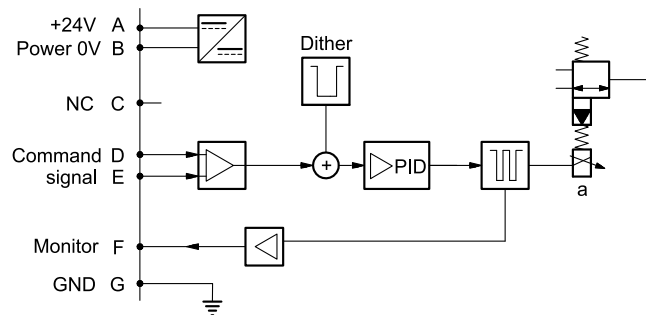
VERSION C - 0V Monitor
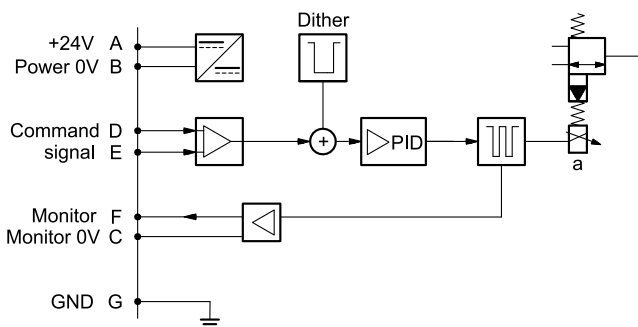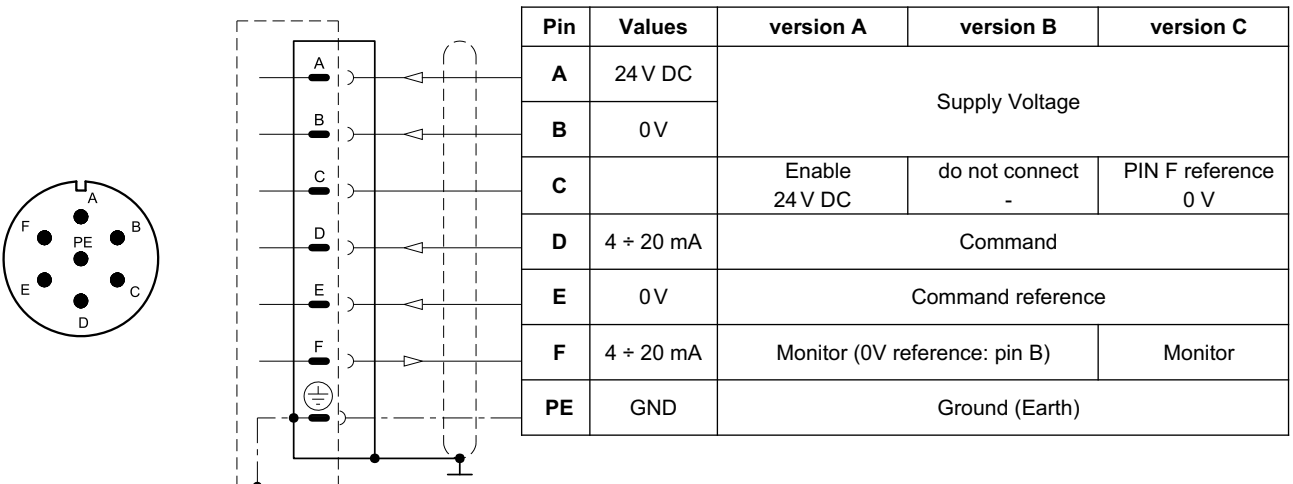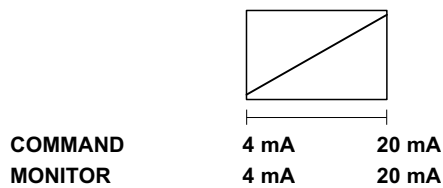
3.3 - Versions with voltage command (E0)

The reference signal is between 0 ÷ 10V. The monitor feature of versions B and C becomes available with a delay of 0,5 sec from the power-on of the card.

COMMAND   0V   +10V
MONITOR   0V   +10V

Pin	Values	version A	version B	version C
A	24 V DC	Supply Voltage		
B	0 V			
C		Enable 24 V DC	do not connect -	PIN F reference 0 V
D	0 ÷ 10 V	Command (differential input)		
E	0 V	Command reference		
F	0 ÷ 10 V	Monitor (0V reference: pin B)		Monitor
PE	GND	Ground (Earth)		

3.4 - Version with current command (E1)

The reference signal is supplied in current 4 ÷ 20 mA. If the current for command is lower the card shows a breakdown cable error. To reset the error is sufficient to restore the signal.

The monitor feature of versions B and C becomes available with a delay of 0,5 sec from the power-on of the card.

COMMAND   4 mA   20 mA
MONITOR   4 mA   20 mA

| Pin	Values	version A	version B	version C
A	24 V DC	Supply Voltage		
B	0 V			
C		Enable 24 V DC	do not connect -	PIN F reference 0 V
D	4 ÷ 20 mA	Command		
E	0 V	Command reference		
F	4 ÷ 20 mA	Monitor (0V reference: pin B)		Monitor
PE	GND	Ground (Earth)		

4 - PZE3GL - COMPACT ELECTRONICS

In versions 'IOL' and 'CA' pin 3 and pin 5 are galvanic isolated up to100 V to avoid earth loops. In IO-Link networks, the length of the connecting cables is limited to 20 metres.

4.1 - Electrical characteristics

Command signal: voltage (E0)	V DC		0 ÷ 10 (Impedance Ri = 11 kOhm)
current (E1)	mA		4 ÷ 20 (Impedance Ri = 58 Ohm)
Monitor signal (current to solenoid): voltage (E0)	V DC		0 ÷ 5 (Impedance Ro > 1 kOhm)
current (E1)	mA		4 ÷ 20 (Impedance Ro = 500 Ohm)
IO-Link communication (IOL): Data rate	kBaud		IO-Link Port Class B 230.4
Can Open communication (CA): Data rate	kbit		10 ÷ 1000
Data register (IOL and CA versions only)			solenoid voltage supply, solenoid faults (shortcircuit, bad config, internal), box temperature, switch-on time, vibrations
Connection			5-pin M12 code A (IEC 61076-2-101)

4.2 - Pin tables

'E0' connection
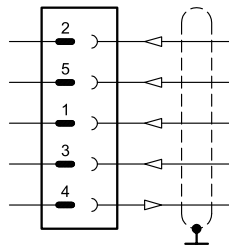
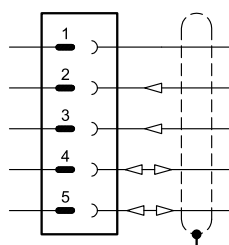| Pin	Values	Function
2	24 V DC	Supply voltage (solenoid and logic)
5	0V	
1	0 ÷ 10 V	Command
3	0V	Command reference
4	0 ÷ 5V	Monitor (0V reference: pin 5)

'E1' connection
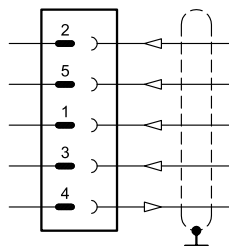
Pin	Values	Function
2	24 V DC	Supply voltage (solenoid and logic)
5	0V	
1	4 ÷ 20 mA	Command
3	0V	Command reference
4	4 ÷ 20 mA	Monitor (0V reference: pin 5)

'IOL' connection
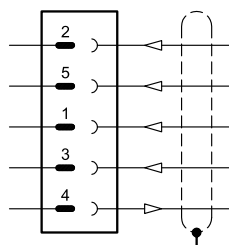
Pin	Values		Function
2	2L+	24 V DC	Supply of the power stage
5	2L-	0 V (GND)	Internal galvanic isolation from PIN 3
1	1L+	+24 V DC	IO-Link supply voltage
3	1L-	0 V (GND)	
4	C/Q		IO-Link Communication

'CA' connection

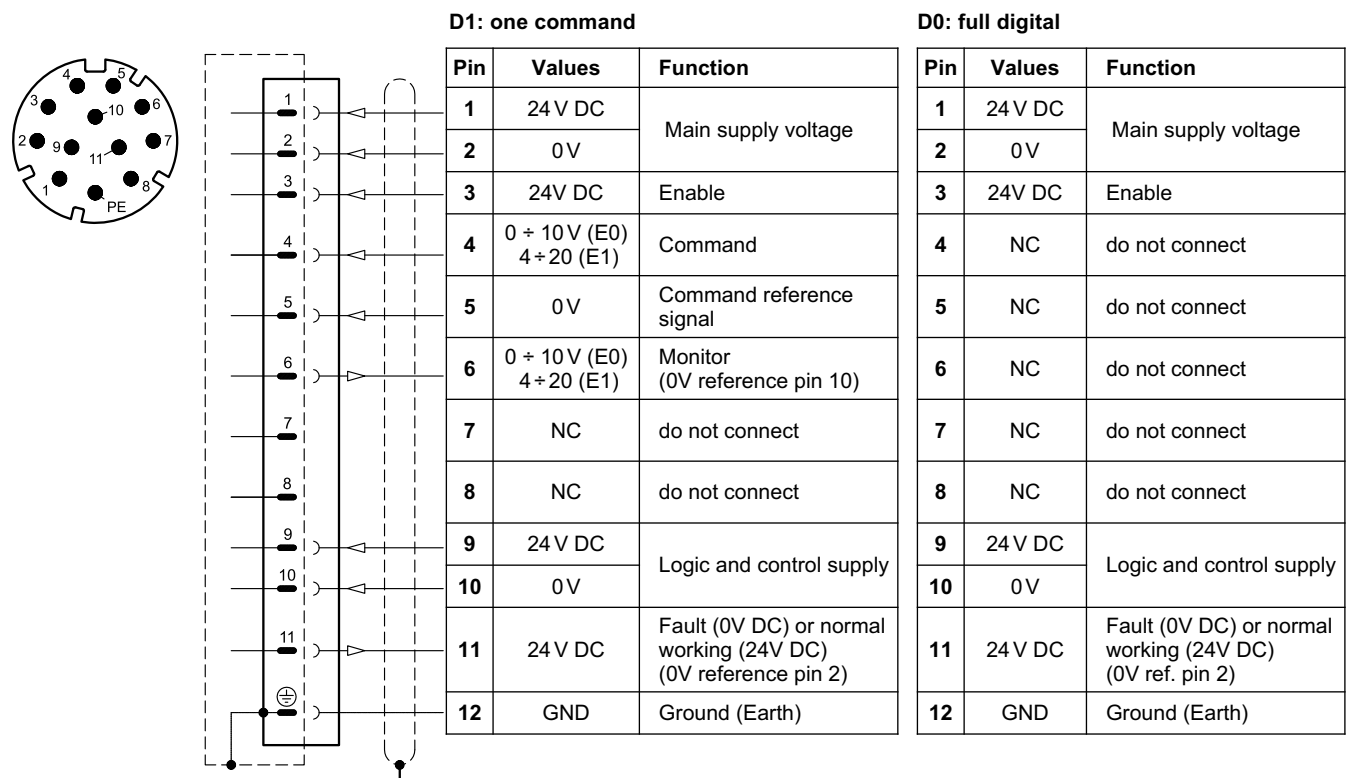| Pin	Values	Function
1	CAN_SH	Shield
2	24 V DC	Supply voltage
3	0 V (GND)	
4	CAN H	Bus line (high)
5	CAN_L	Bus line (low)

5 - PZE3GH - FIELDBUS ELECTRONICS

The 11+ PE pin connection allows separate supply voltage for electronics and solenoid.

Command - valve position schemes as for the standard electronics. Please refer to pictures in par. 3.3 and 3.4.

5.1 - Electrical characteristics

Command signal:		
voltage (E0) current (E1) digital (FD)	V DC mA	0 ÷ 10 (Impedance Ri = 11 kOhm) 4 ÷ 20 (Impedance Ri = 58 Ohm) via fieldbus
Monitor signal (current to solenoid): voltage (E0) current (E1)	V DC mA	0 ÷ 10 (Impedance Ro > 1 kOhm) 4 ÷ 20 (Impedance Ro = 500 Ohm)
Communication / diagnostic		via Bus register
Communication interface standards		IEC 61158
Communication physical layer		fast ethernet, insulated 100 Base TX
Power connection		11 pin + PE (DIN 43651)

5.2 - X1 Main connection pin table

D1: one command

Pin	Values	Function
1	24 V DC	Main supply voltage
2	0 V	Main supply voltage
3	24V DC	Enable
4	0 ÷ 10 V (E0) 4 ÷ 20 (E1)	Command
5	0 V	Command reference signal
6	0 ÷ 10 V (E0) 4 ÷ 20 (E1)	Monitor (0V reference pin 10)
7	NC	do not connect
8	NC	do not connect
9	24 V DC	Logic and control supply
10	0 V	Logic and control supply
11	24 V DC	Fault (0V DC) or normal working (24V DC) (0V reference pin 2)
12	GND	Ground (Earth)

D0: full digital

Pin	Values	Function
1	24 V DC	Main supply voltage
2	0 V	Main supply voltage
3	24V DC	Enable
4	NC	do not connect
5	NC	do not connect
6	NC	do not connect
7	NC	do not connect
8	NC	do not connect
9	24 V DC	Logic and control supply
10	0 V	Logic and control supply
11	24 V DC	Fault (0V DC) or normal working (24V DC) (0V ref. pin 2)
12	GND	Ground (Earth)

5.3 - FIELDBUS connections

Please wire following guidelines provided by the related standards communication protocol. Any connections present and not used must be protected with special caps so as not to nullify the protection against atmospheric agents.

X2 (IN) connection M12 D 4 pin female

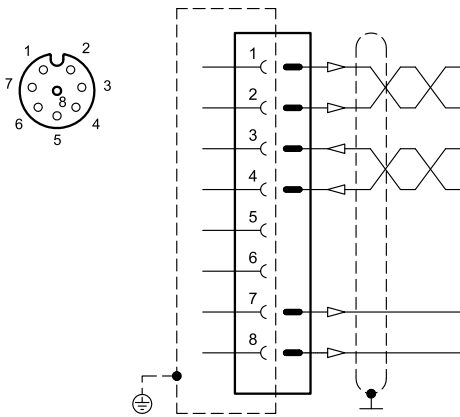| Pin	Values	Function
1	TX+	Transmitter
2	RX+	Receiver
3	TX-	Transmitter
4	RX-	Receiver
HOUSING	shield	

X3 (OUT) connection: M12 D 4 pin female

Pin	Values	Function
1	TX+	Transmitter
2	RX+	Receiver
3	TX-	Transmitter
4	RX-	Receiver
HOUSING	shield	

NOTE: Shield connection on connector housing is recommended.

5.4 - Digital transducer connection
X7 connection: M12 A 8 pin female

VERSION 1: SSI type

Pin	SSI Values	Function	Notes
1	CLK+	Serial synchronous clock (+)	Input - digital signal
2	CLK-	Serial synchronous clock (-)	
3	MIS0+	Serial position data (+)	
4	MIS0-	Serial position data (-)	
5	NC	-	do not connect
6	NC	-	
7	+24 V	transducer power supply	Output power supply
8	0 V	-	Common GND

VERSION 2: ENCODER type
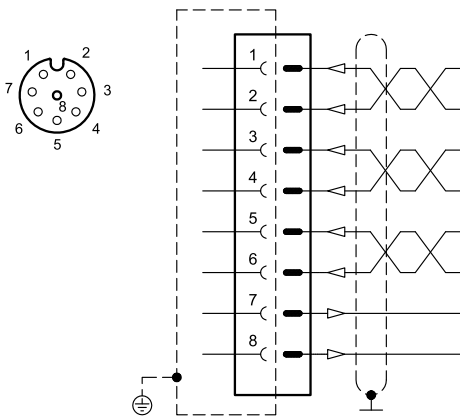
Pin	Values	Function	Notes
1	ENC_Z+	input channel Z+	Input - digital signal
2	ENC_Z-	input channel Z-	
3	ENC_A+	input channel A+	
4	ENC_A-	input channel A+	
5	ENC_B+	input channel B+	
6	ENC_B-	input channel B+	
7	+5 V	transducer power supply	Output power supply
8	0 V	-	Common GND

5.5 - Analogue transducer connection
X4 connection: M12 A 4 pin female

VERSION 1: single / double transducer
(single or double is a software-selectable option)
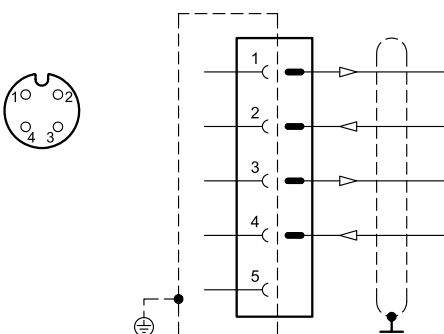
| Pin	Values	Notes
1	+24 V	Remote transducer power supply (out) 100 mA
2	±10 V 4 ÷20 mA	Input signal of transducer 1 (range software selectable)
3	0 V	Common reference signal for transducer power and signals
4	±10 V 4 ÷20 mA	Input signal of transducer 2 (range software selectable)
5	-	

6 - CHARACTERISTIC CURVES
(measured with viscosity of 36 cSt at 50°C)

Typical control characteristics, according to the reference signal for available pressure control ranges. Characteristic curves measured without backpressure in T, with linearity compensation set by the onboard electronics.
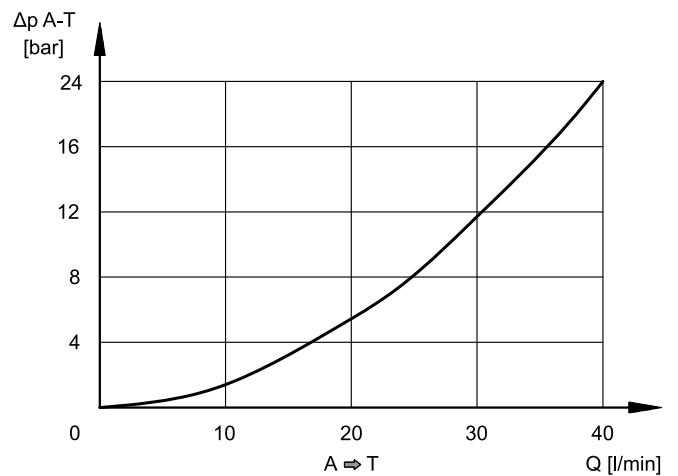
PRESSURE CONTROL p = f (I)
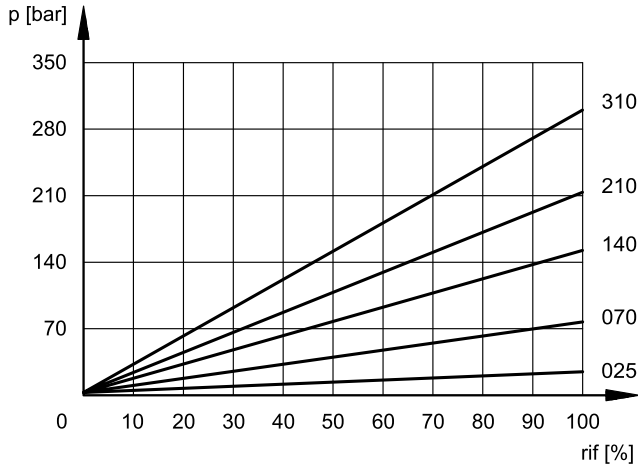
SET PRESSURE p max = f (Q)
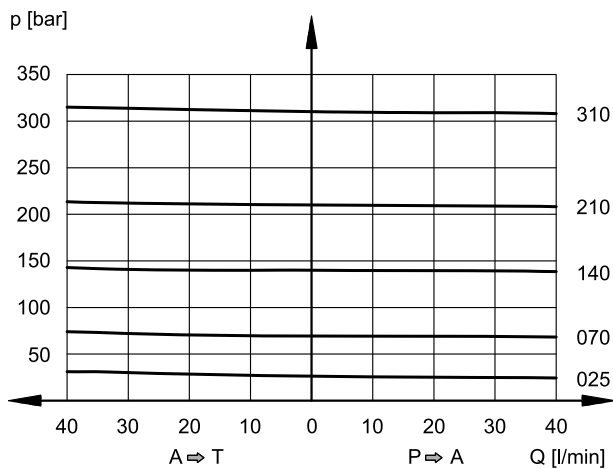
MIN. CONTROLLED PRESSURE p min = f (Q)

Pressure drops A →T vs. flow, without backpressure in T port and reference signal = 0 %
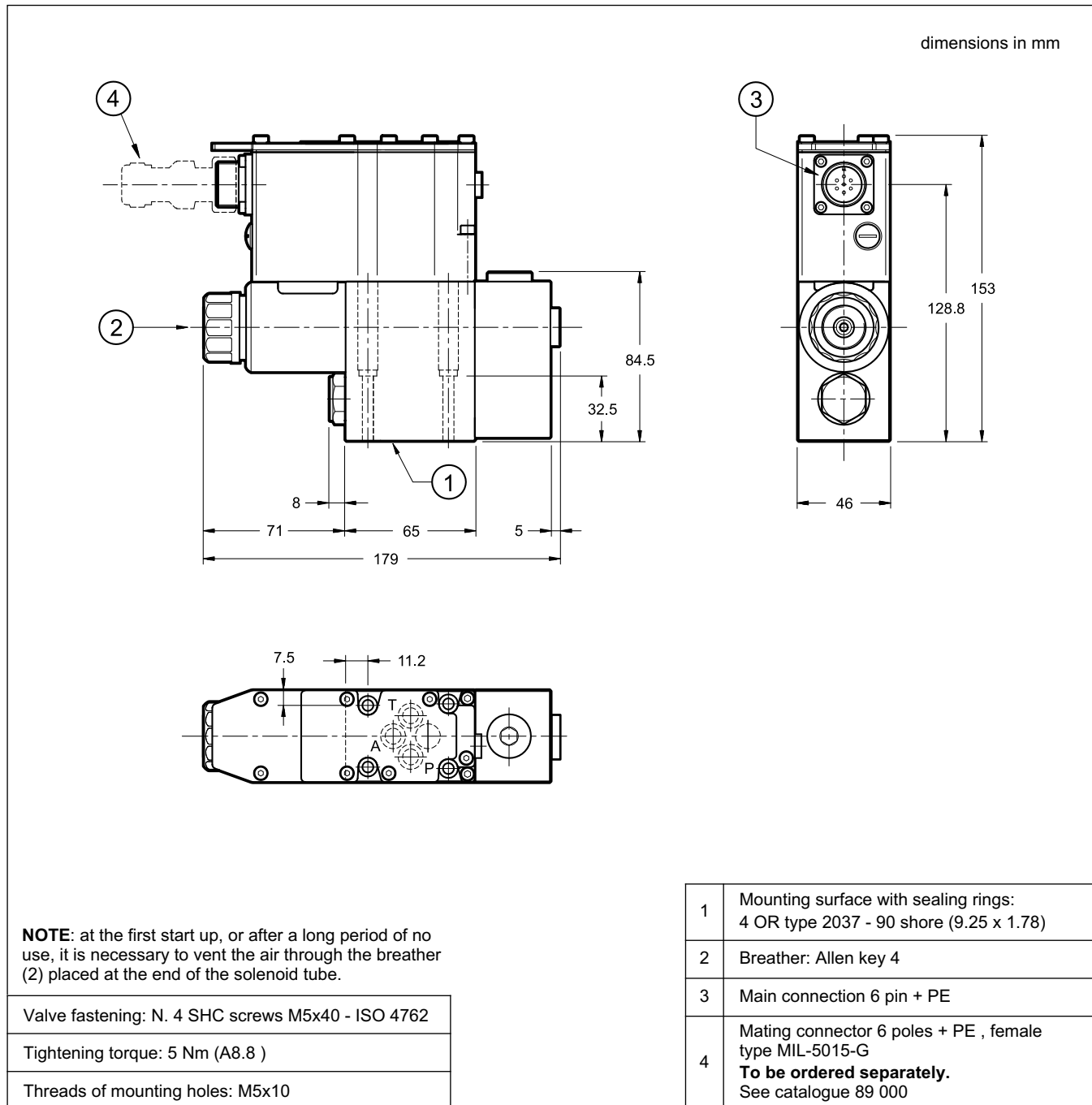
7 - RESPONSE TIMES
(obtained with mineral oil with viscosity of 36 cSt at 50°C)

Step response is the time taken for the valve to reach 90% of the set pressure value following a step change of reference signal.

The response time is affected both by the flow rate and the oil volume in the pipework.
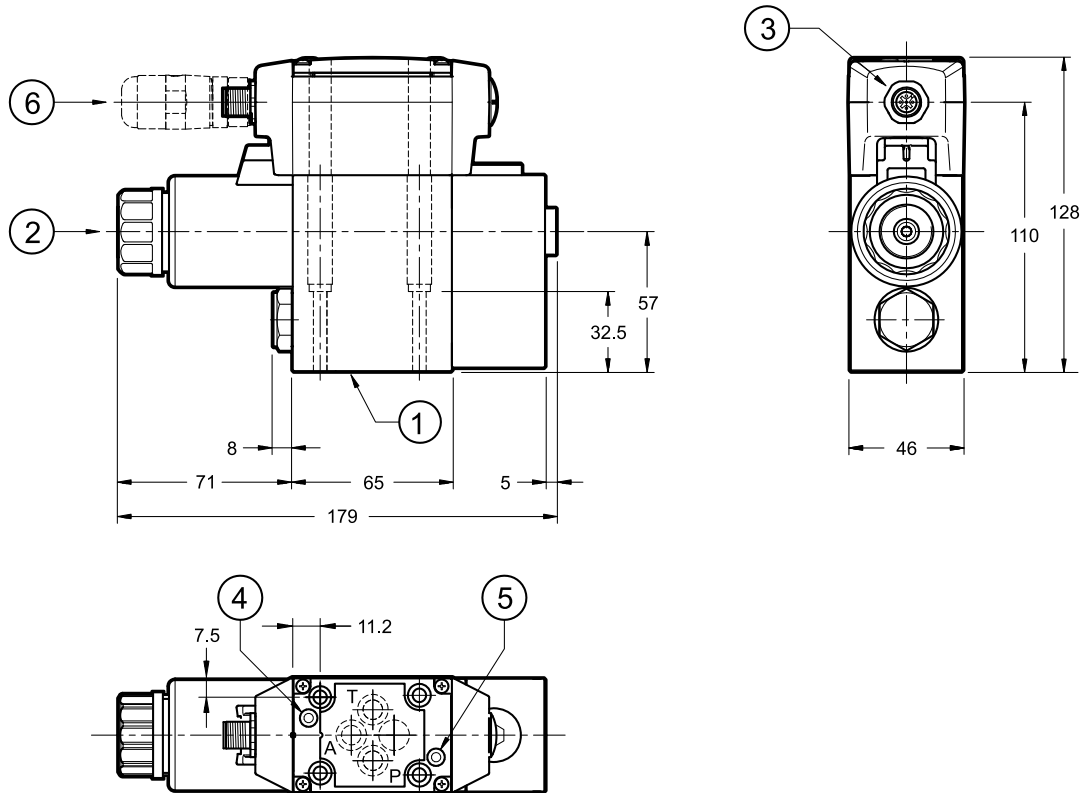
REFERENCE SIGNAL STEP	0 → 100%	100 → 0%
Step response [ms]	80	80

PZE3G*

8 - PZE3G - OVERALL AND MOUNTING DIMENSIONS

dimensions in mm

NOTE: at the first start up, or after a long period of no use, it is necessary to vent the air through the breather (2) placed at the end of the solenoid tube.

Valve fastening: N. 4 SHC screws M5x40 - ISO 4762	
Tightening torque: 5 Nm (A8.8)	
Threads of mounting holes: M5x10	

1	Mounting surface with sealing rings: 4 OR type 2037 - 90 shore (9.25 x 1.78)
2	Breather: Allen key 4
3	Main connection 6 pin + PE
4	Mating connector 6 poles + PE , female type MIL-5015-G **To be ordered separately.** See catalogue 89 000

9 - PZE3GL - OVERALL AND MOUNTING DIMENSIONS

dimensions in mm

NOTE: at the first start up, or after a long period of no use, it is necessary to vent the air through the breather (2) placed at the end of the solenoid tube.

| Valve fastening: N. 4 SHC screws M5x40 - ISO 4762 |
|---|
| Tightening torque: 5 Nm (A8.8) |
| Threads of mounting holes: M5x10 |

1	Mounting surface with sealing rings: N. 4 OR type 2037 (9.25x1.78) 90 Shore
2	Breather: Allen key 4
3	Connection M12 A 5 pin
4	L1 LED
5	L2 LED
6	Mating connector M12 5 poles - code A, female **To be ordered separately.** See catalogue 89 000

10 - PZE3GH - OVERALL AND MOUNTING DIMENSIONS

dimensions in mm
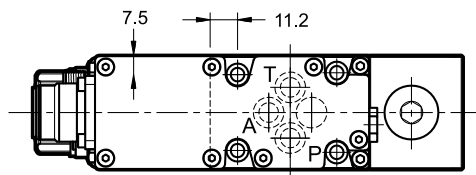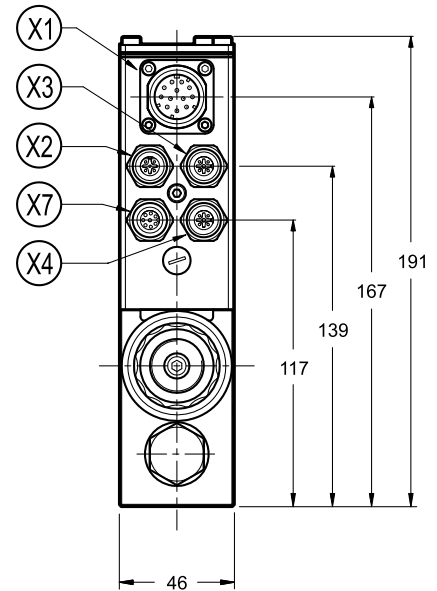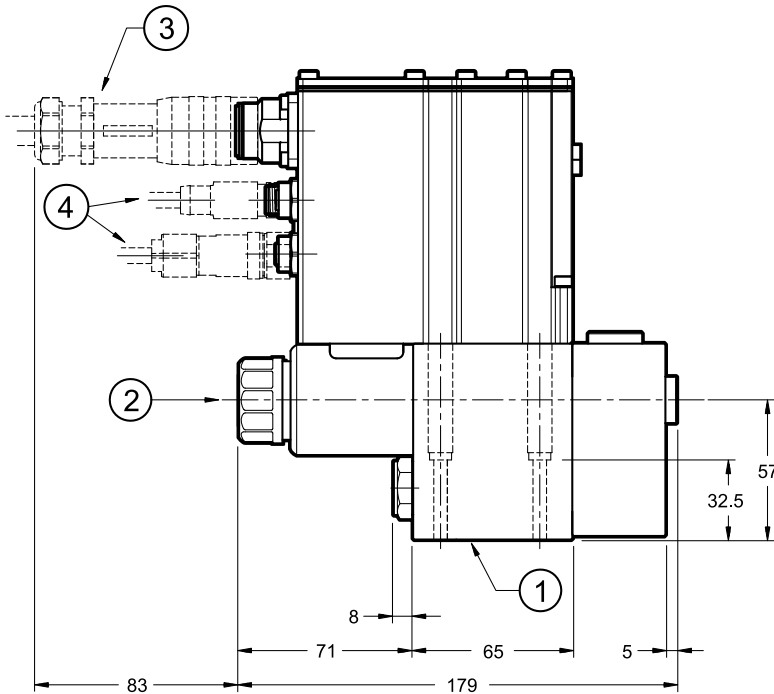
X1	Main connection 11 pin + PE
X2	Fieldbus communication (IN)
X3	Fieldbus communication (OUT)
X4	X4 connection for analogue transducer
X7	X7 connection for digital transducer

1	Mounting surface with sealing rings: N. 4 OR type 2037 (9.25x1.78) 90 Shore
2	Breather: Allen key 4
3	Mating connector 11 poles + PE **To be ordered separately.** See catalogue 89 000
4	Mating connectors for fieldbus communication and signals **To be ordered separately.** See catalogue 89 000

NOTE 1: at the first start up, or after a long period of no use, it is necessary to vent the air through the breather (2) placed at the end of the solenoid tube.

NOTE 2: Depending on the chosen version, X4 and X7 connections may not be present.

Please refer to section 5 for connection descriptions and pinout.

Fastening bolts: 4 bolts M5x40 - ISO 4762
Torque: 5 Nm (A8.8)
Threads of mounting holes: M5x10

11 - HYDRAULIC FLUIDS

Use mineral oil-based hydraulic fluids HL or HM type, according to ISO 6743-4. For these fluids, use NBR seals. For fluids HFDR type (phosphate esters) use FPM seals (code V). For the use of other kinds of fluid such as HFA, HFB, HFC, please consult our technical department.

Using fluids at temperatures higher than 80 °C causes a faster degradation of the fluid and of the seals characteristics. The fluid must be preserved in its physical and chemical characteristics.

12 - INSTALLATION

We recommend to install the valves either in horizontal position, or vertical position with the solenoid downward. If the valve is installed in vertical position and with the solenoid upward, you must consider possible variations of the minimum controlled pressure, if compared to what is indicated in section 6.

Ensure that there is no air in the hydraulic circuit. In particular applications, can be necessary to vent the air entrapped in the solenoid tube, by using the appropriate drain screw in the solenoid tube. So, ensure the solenoid tube is always filled with oil. When finished, make sure you have screwed the screw back in correctly.

Connect the valve T port directly to the tank. Add any backpressure value detected in the T line to the controlled pressure value. Maximum admissible backpressure in the T line, under operational conditions, is 2 bar.

Valves are fixed by means of screws or tie rods on a flat surface with planarity and roughness equal to or better than those indicated in the relative symbols. If minimum values are not observed, fluid can easily leak between the valve and support surface.

Surface finishing

0.01/100

0.8
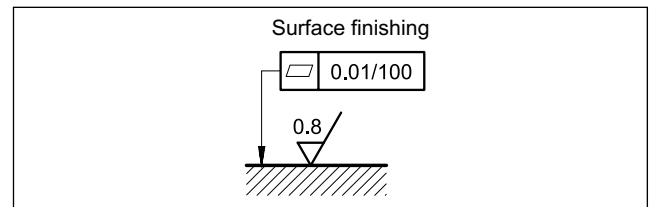
13 - ACCESSORIES
(to be ordered separately)

13.1 - Mating connectors

Mating connectors must be ordered separately. See catalogue 89 000.

For K11 and K16 versions we recommend the choice of a metal connector to avoid electromagnetic disturbances and to comply with EMC regulations on electromagnetic compatibility. If you opt for a plastic connector, make sure that it guarantees and maintains the IP and EMC protection characteristics of the valve.

13.2 - Mating connectors and caps for fieldbus communication and for sensors.

Duplomatic offers spare parts to be wired and also ready-to-use cord sets. Please refer to cat. 89 000.

13.3 - Connection cable

The optimal wiring provides for 7 isolated conductors, with separate screen for the signal wires (command, monitor) and an overall screen.

Cross section for power supply:
- up to 20 m cable length : 1,0 mm^2
- up to 40 m cable length : 1,5 mm^2 (IO-Link excluded)

Cross section for signals (command, monitor):
- 0,50 mm^2

13.4 - Kit for start-up LINPC-USB

Device for service start-up and diagnostic. See catalogue 89 850.

14 - SUBPLATES
(see catalogue 51 000)

PMMD-AI3G with ports on rear
PMMD-AL3G with side ports
Ports dimensions P, T, A, B: 3/8" BSP thread