



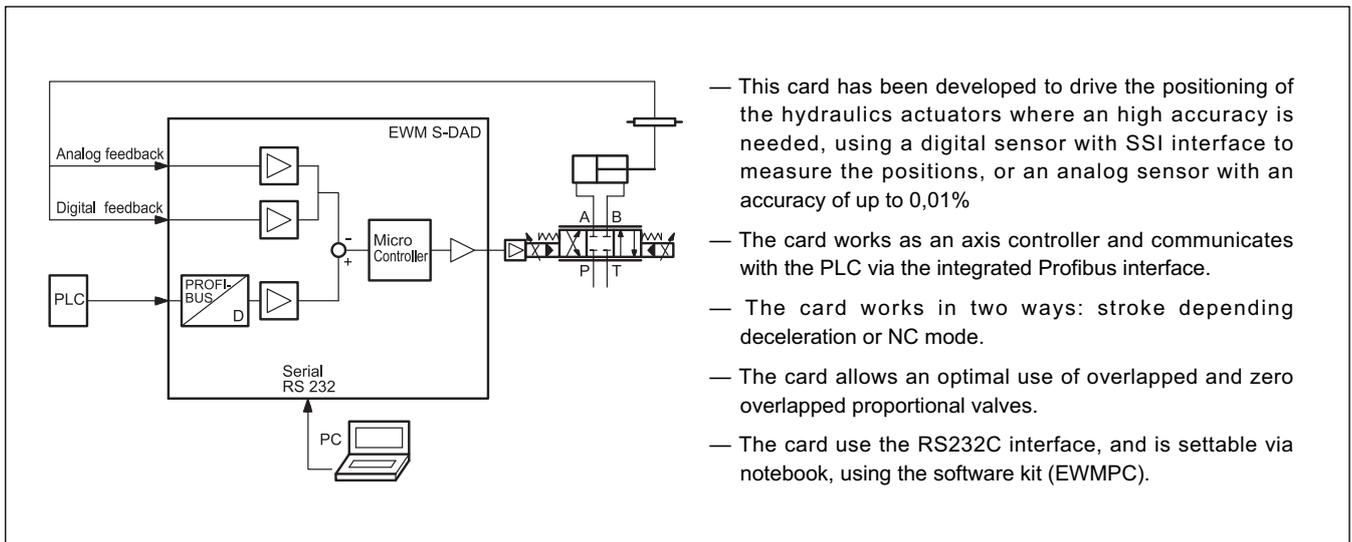
EWM-S-DAD

CARD FOR POSITIONING AND VELOCITY STROKE CONTROL WITH PROFIBUS COMMUNICATION INTERFACE

SERIES 10

**RAIL MOUNTING TYPE:
DIN EN 50022**

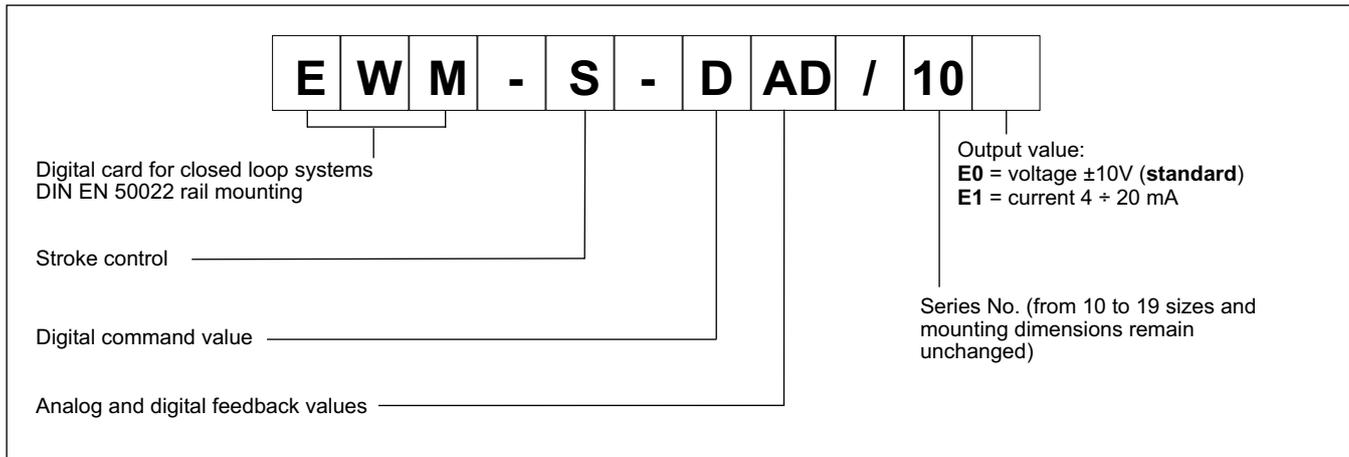
OPERATING PRINCIPLE



TECHNICAL CHARACTERISTICS

Power supply	V DC	12 ÷ 30 ripple included - external fuse 1,0 A
Current consumption	mA	400+ sensor power consumption
Command value		via Profibus DP - ID number 1810h
Feedback value	V mA SSI	0 ÷ 10 (R _I = 33 kΩ) 4 ÷ 20 (R _I = 250 Ω) digital sensor with any interface SSI
Output value: - E0 version - E1 version	V mA	±10 (max load 5 mA) 4 ÷ 20 (max load 390 Ω)
Position accuracy	%	± 2 bits of sensor resolution
Interface		RS 232 C
Electromagnetic compatibility (EMC): according to 2004/108/CE standards		Emissions EN 61000-6-3 Immunity EN 61000-6-2
Housing material		thermoplastic polyamide PA6.6 combustibility class V0 (UL94)
Housing dimensions	mm	120 (d) x 99(h) x 46(w)
Connector		4x4 poles screw terminals - PE direct via DIN rail
Operating temperature range	°C	-20 / +60
Protection degree		IP 20

1 - IDENTIFICATION CODE



The card EWM-S-DAD is an evolution of an analog model (EWM-S-AD). The customer can choose between two sensor types: analog or digital and the communication with the PLC is via Profibus DP.

With only a few parameters the controller can be optimized and the movement profile is preset via Profibus (position and velocity).

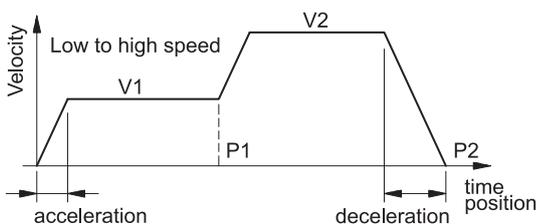
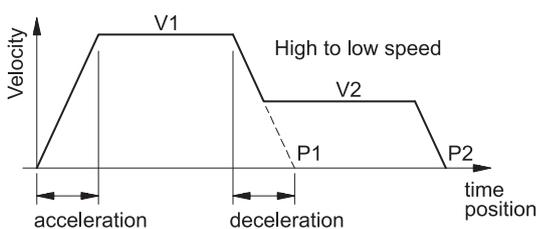
Here below an example of profile with a switch speed:

- the target position is command value 2 (P2) combined with velocity 2 (V2).
- the switch over position is command value 1 (P1), combined with velocity 1 (V1).

Switching over position from a high to a lower speed is calculated by the deceleration function and V2.

Switching over from a low to a high velocity is carried out at the position (P1) via the acceleration ramp; see below.

- If the positioning command value 2 (P2) is between the actual and the position command value 1 (P1), to position 2 (P2) can only be driven with speed 1 (V1).



2- FUNCTIONAL SPECIFICATIONS

2.1 - Power supply

This card is designed for 12 to 30 VDC (typical 24 V) of a power supply. This power supply must correspond to the actual EMC standards.

All inductivities at the same power supply (relays, valves) must be

provided with an over voltage protection (varistors, free-wheel diodes).

It is recommended to use a regulated power supply (linear or switching mode) for the card supply and for the sensors.

2.2 - Electrical protections

All input and output are protected against overvoltage and have filters.

2.3 - Digital Input (ENABLE)

The card accepts digital input. The digital input must have a voltage from 12 to 24 V with current $< 0,1A$. See the block diagram at paragraph 8 for the electric connections.

2.4 - Command value

The card accepts the input via Profibus, ID number 1810h (see paragraph 4)

2.5 - Input feedback values

The card accepts analog or digital feedback input. The digital sensor parameters are settable via software (see parameters table).

2.6 - Output values

The card is designed for two type of output values, voltage $\pm 10V$ (E0 version) or current $4 \div 20$ mA (E1 version); standard output value is E0 type.

2.7 - Digital Output

Two digital output are available, INPOS and READY, and their signals are displayed from the leds. The output are available on PIN1 and PIN2. The output is 24V. The PIN 4 is used as common potential 0V. (I_{max} 50 mA with load of 200 Ω).

3 - LED FUNCTIONS

There are three leds on the card: one on the profibus module, that indicates the online status of Profibus connection, and two on the other module:

GREEN: Shows if the card is ready.

ON - The card is supplied

OFF - No power supply

FLASHING - Failure detected (internal or 4... 20 mA).

Only if SENS = ON

YELLOW: Is the signal of the control error monitoring.

ON - No control error

OFF - Error detected, depending of a parameter error.



EXAMPLE OF PARAMETERS TABLE

Commands	Parameter	Defaults	Units	Description
inpx	X= SSI ANA	SSI	-	Selection of the sensor input channel.
pdpadr x	X= 1... 126	5		profibus address
ain:i a b c x	i= W X a= -10000... 10000 b= -10000... 10000 c= -10000... 10000 x= V C	: 10000 : 10000 : 0 : V	- - 0,01% -	Analogue input scaling. XL for the input and V = voltage. C = current. With the parameters a , b and c the inputs can be scaled (output = a / b * (input - c)). Because of the programming of the x -value (x = C) the corresponding input will be switched over to current automatically.
a:i x	i= A B x= 1... 2000	:A 200 :B 200	ms ms	Acceleration time depending on direction. A indicates analogue output 15 and B indicates analogue output 16. Normally A = flow p-A, B-T and B = flow P-B, A-T.
d:i x	i= A B S X= 50... 10000	:A 2500 :B 2500 :S 1000	0,01% 0,01%	Deceleration stroke depending on direction. The loop gain is calculated by the deceleration stroke. The shorter the higher. In case of instabilities longer deceleration stroke will be sufficient.
ctrl x	x= lin sqrt1 sqrt2	sqrt1	-	Selection of the control function: lin = standard linear P-control, sqrt1 = progressive time optimized deceleration curve sqrt2 = sqrt1 with a higher gain in position
stroke x	X= 2... 3000	500	mm	Sensor stroke.
ssioffset X	X= -30000... 30000	0	0,01 mm	Zero point adjustment of the sensor.
ssires X	X= 1... 1000	1000	ink/mm	Resolution of the sensor.
ssibits x	X= 8... 31	24	-	Bits of the data word.
ssicode x	X= GRAY BIN	GRAY	-	Format of the data word.
ssipol x	X= + -	+	-	Sensor polarity, attention: SSI OFFSET has to be set to compensate negative position values.
vramp x	x= 1... 2000	50	ms	Ramp time for velocity input.
vmax x	X= 1... 20000	50	mm/s	Parameter is active in vmode = ON only. VEL defines the maximum speed. Via the external command speed an actual speed between 0,5... 100 % can be selected.
vmode x	x= on off	off	-	Activation of the NC-generator. The command position is generated by a velocity profile (internal or external preset of v). The axis drives more or less speed controlled.
hand:i x	i= A B x= -10000... 10000	:A 3300 :B -3300	0,01% 0,01%	Degree of output signal in manual mode
min:i x	i= A B x= 0... 5000	:A 0 :B 0	0,01% 0,01%	Deadband compensation of positive overlapped proportional valves. Good adjustment will increase positioning accuracy.
max:i x	i= A B x= 5000... 10000	:A 10000 :B 10000	0,01% 0,01%	Maximum output range for adapting control range to maximum flow range.
trigger x	x= 0... 2000	200	0,01%	Point to activate the deadband compensation (min). Also useful for reduced sensitivity in position with control valves.
dc:i x	i= I AV DV RA I:x = 3... 30000 AV:x = 0... 10000 DV:x = 0... 10000 RA:x = 0... 10000	I:x 1300 AV:x 0 DV:x 0 RA:x 500	ms 0,01% 0,01% 0,01%	Activation and adjustment of the Drift-compensator. If necessary, the drift compensation with "DC: AV x" in a catchment area activated and the target range by "DC: DV x" disabled. "DC: I x", the time constant and "DC: RA x" value area of the integrator.
inpos x	X= 0... 5000	32	0,01%	Range for the InPos signal (status output).
offset x	x= -2000... 2000	0	0,01%	The offset will be added to the command value.
pol x	x= + -	+	-	For changing the output polarity. All A and B adjustments depend on the output polarity. The right polarity should be defined first.
save	-	-	-	Storing the programmed parameter in E ² PROM.
loadback	-	-	-	Reloading the parameter from E ² PROM in working RAM
upload	-	-	-	Parameter list with programmed data, for terminal programs only
st	-	-	-	Status of the digital inputs.
wl, xl, xw, u, v	-	-	-	Actual signals: command value, actual value, process data, control divergence and reference value.
default	-	-	-	Preset values will be set.



4 - PROFIBUS DP LINKING

4.1 Profibus functions

The module supports all baud rates from 9,6 kbit/s up to 12000 kbit/s with auto detection of the baud rate. The functionality is defined in IEC 61158. The Profibus address can be programmed by a terminal program, EWMPC/10 or online via the Profibus. A diagnostic LED indicates the online status.

4.2 Installation

A typical screened Profibus plug (D-Sub 9pol with switchable termination) is mandatory.

Every Profibus segment must be provided with an active bus termination at the beginning and at the end. The termination is already integrated in all common Profibus plugs and can be activated by DIL switches.

The Profibus cable must be screened. PIN 17 have to be connected with PE (low impedance).

Byte	Function	Comment	
1	control word Hi		
2	control word Lo	actual not used	
3	command position 1 Hi		
4	command position 1		
5	command position 1		
6	command position 1 Lo		
7	velocity 1 Hi		
8	velocity 1 Lo		
9	command position 2 Hi		active, if a second velocity is programmed (Bytes 13 and 14)
10	command position 2		
11	command position 2		
12	command position 2 Lo		
13	velocity 2 Hi		
14	velocity 2 Lo		
15	-	reserved	
16	-	reserved	

the definition of the control word are:

Byte 1 - control word Hi		
bit	Function	
8	Enable (with hardware enable)	1 = ready
7	Start	1 = active
6	Hand-	1 = active
5	Hand+	1 = active
4		
3		
2		
1		

Byte 3 to 6 - command position 1		
bit	Function	
from 25 to 32	Command position Hi byte	defined by the sensor resolution
from 17 to 24		
from 9 to 16		
from 1 to 8	Command position Lo byte	

Byte 7 and 8 - command velocity 1		
bit	Function	
from 9 to 16	velocity Hi byte	max 3f hex
from 1 to 8	velocity Lo byte	max ff hex

Byte 9 to 12 - command position 2		
bit	Function	
from 25 to 32	Command position Hi byte	defined by the sensor resolution
from 17 to 24		
from 9 to 16		
from 1 to 8	Command position Lo byte	

Byte 13 and 14 - command velocity 2		
bit	Function	
from 9 to 16	velocity Hi byte	max 3f hex
from 1 to 8	velocity Lo byte	max ff hex

The enable bit is combined with the external enable input; that means that both signals must exist, in order to enable the axes.

4.3 Data sent to the profibus

Totally, 16 bytes will be sent to the Profibus.

Byte	Function	Comment
1 (0)	status word Hi	
2 (1)	status word Lo	not used
3 (2)	actual position Hi	
4 (3)	actual position	
5 (4)	actual position	
6 (5)	actual position Lo	
7 (6)	internal command position Hi	
8 (7)	internal command position	
9 (8)	internal command position	
10 (9)	internal command position Hi	
11 (10)		
12 (11)		
13 (12)		
14 (13)		
15 (14)		
16 (15)		



the status word are:

Byte 1 - status word Hi		
bit	Function	
8	READY	1 = ready to operate
7	INPOS	1 = actual value in position window
6		
5		
4		
3		
2		
1		

Byte 3 and 4 - command position		
byte	Function	
from 25 to 32	Command position Hi-Byte	in resolution of the positioning sensor
from 17 to 24	Command position	
from 9 to 16	Command position	
from 1 to 8	Command position Lo-Byte	

Byte 5 and 6 - internal command position		
byte	Function	
from 25 to 32	Command position Hi-Byte	in resolution of the positioning sensor
from 17 to 24	Command position	
from 9 to 16	Command position	
from 1 to 8	Command position Lo-Byte	

5 - ADJUSTMENTS

On the EWM card family, the adjustment setting is possible only via software. Connecting the card to the PC, the software automatically recognises the card model, and shows a table (see example at page 3) with all the available parameters, with their commands, the default setting, the measuring unit and an explanation of the command and its uses. The parameters changes depending on the card model, and they are fully described in the *Overhaul manual*.

6 - INSTALLATION

The card is designed for rail mounting type DIN EN 50022.

The wiring connections are on the terminal strip located on the bottom of the electronic control unit. It is recommended to use cable sections of 0.75 mm², up to 20 m length and of 1.00 mm² up to 40m length, for power supply and solenoid connections. For other connections it is recommended to use cables with a screened sheath connected to earth only on the card side.

NOTE 1

To observe EMC requirements it is important that the control unit electrical connection is in strict compliance with the wiring diagram.

As a general rule, the valve and the electronic unit connection wires must be kept as far as possible from interference sources (e.g. power wires, electric motors, inverters and electrical switches).

In environments that are critical from the electromagnetic interference point of view, a complete protection of the connection wires can be requested.

7- SOFTWARE KIT EWMP/10 (code 3898401001)

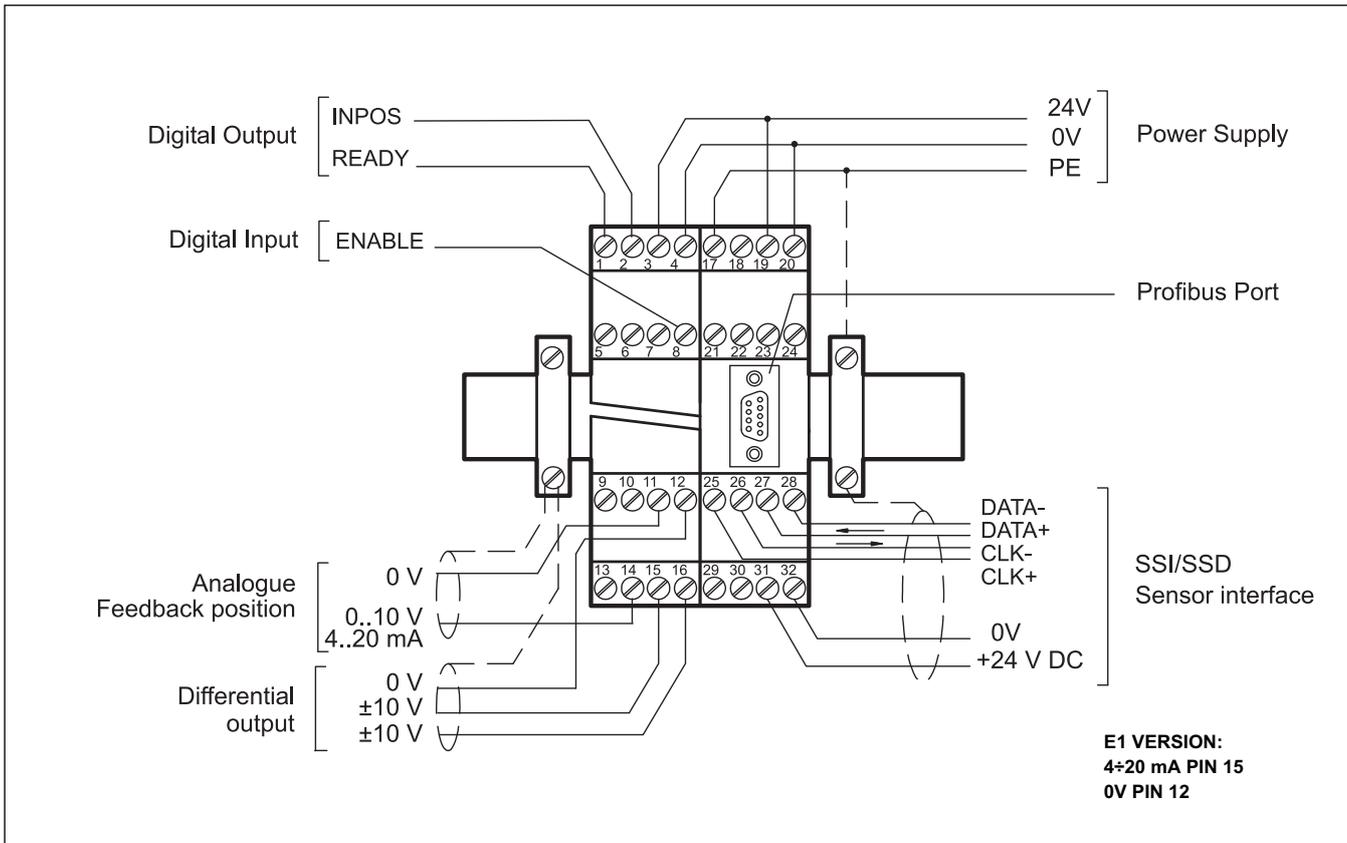
The software kit comprising a USB cable (2.70 mt lenght) to connect the card to a PC or notebook and the software.

During the identification all information are read out of the module and the table input will be automatically generated.

Some functions like baud rate setting, remote control mode, saving of process data for later evaluation are used to speed up the installation procedure.

The software is compliant with Microsoft XP® operating systems.

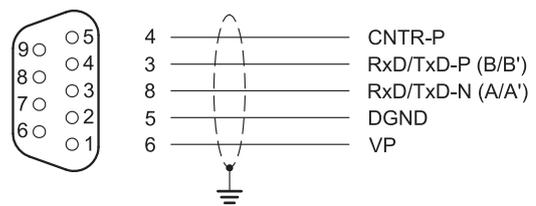
8 - WIRING DIAGRAM



DIGITAL INPUT AND OUTPUT

- PIN 1** READY output.
General operability, ENABLE is active and there is no sensor error (by use of 4+20 mA sensors). This output corresponds with the green LED.
- PIN 2** INPOS output.
Monitoring of the control error (INPOS). Depending on the INPOS command, the status output will be deactivated, if the position difference is greater then the adjusted window.
The output is only active if START = ON.
- PIN 8** ENABLE input:
This digital input signal initializes the application. The analogue output is active and the READY signal indicates that all components are working correctly. Target position is set to actual position and the drive is closed loop controlled.

PROFIBUS PORT WIRING AND LINKING CONFIGURATION

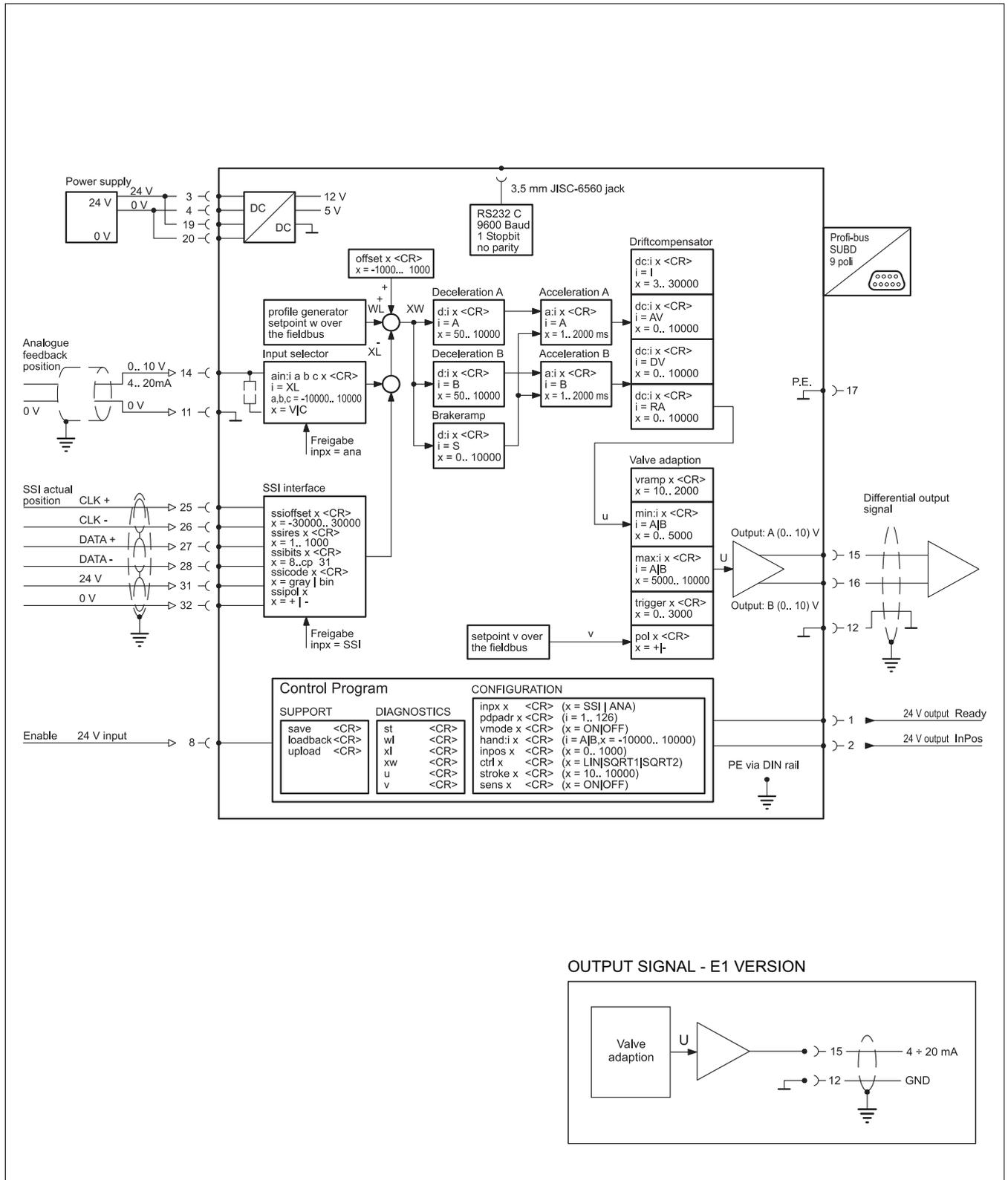


pin	Signal name	Function
1-2-7-9	not used	-
3	RxD/TxD-P (B-Line)	Receive/Send P data
4	CNTR-P/RTS	Request to Send
5	DGND	Data ground
6	VP	+5 V DC for external bus termination
8	RxD/TxD-N (A-Line)	Receive/Send N data

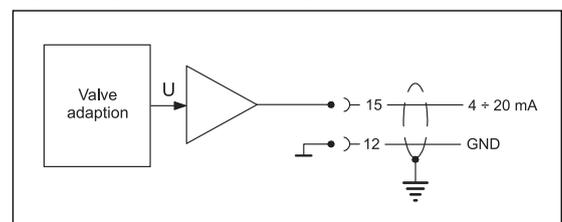
ANALOGUE INPUT AND OUTPUT

- PIN 14** Analogue feedback value (X),
range 0 ÷ 100% corresponds to 0 ÷ 10V or 4 ÷ 20 mA
- PIN 15/16** Differential output (U)
±100% corresponds to ± 10V differential voltage, optionally (E1 version) current output ±100% corresponds to 4 ÷ 20 mA (PIN 15 to PIN 12)

9 - CARD BLOCK DIAGRAM

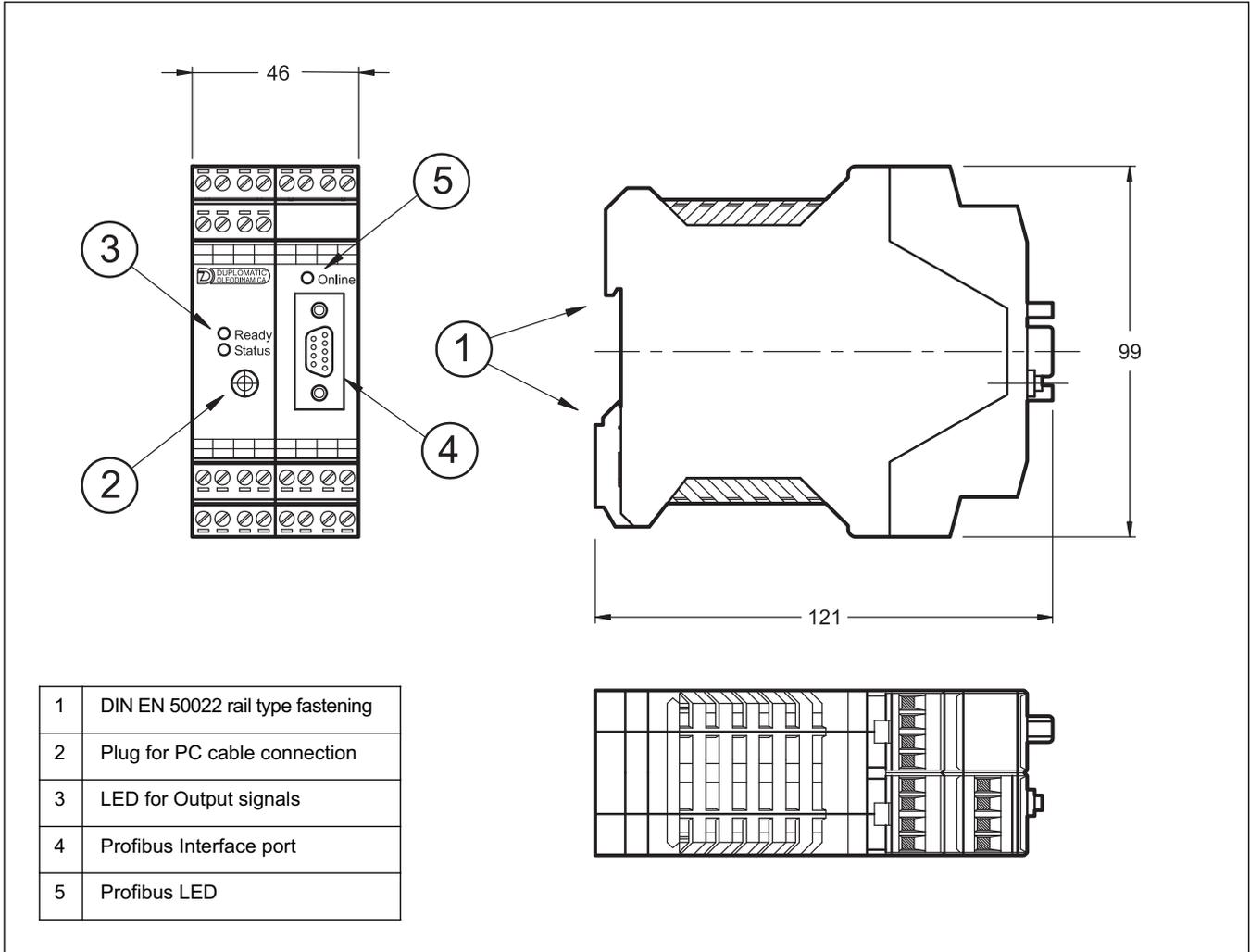


OUTPUT SIGNAL - E1 VERSION





10 - OVERALL AND MOUNTING DIMENSIONS



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